

Ingmar Wegner





- DataNodes are stored within DataStorage and are parsed during rendering. One datum is connected to one DataNode
- Visualization is done by VTK
- Image processing is done by ITK
- MITK is GUI independent, MITK ExtApp uses QT

See hyperlinks to doxygen documentation for further reading

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Interaction

Contents

- What's this?
- Feature requests for MITK
- Solution (state machines)
- Example interaction sequence
- Undo (/ Redo)
 - Feature requests
 - Example undo sequence



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User can modify data during runtime using input devices.





What is interaction?



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Interaction:

- Representation of complex workflows
- Possibility to quickly modify the interaction
- Reuse of interaction
- Independent from GUI toolkit
- User- and developer-friendly
- Allows flexibility
- Not dependent on visualization (2D / 3D)

Undo:

- Offer flexible undo / redo functionality
- Save memory resources

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Interaction:

- Representation of complex workflows
 - So use state machines (Mealy / More)
- Possibility to quickly modify the interaction
 - ➢Without recompile? Then use a generic way of loading interaction patterns during startup.
- Reuse of interaction
 - ≻Then one interactor per data object and the developer defines what it does. Several equivalent data objects use the same interaction pattern.

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- Independent from GUI toolkit
 - ≻Create a layer in between
- User- and developer-friendly
 - Swiss army knife?* / *Eierlegende Woll-Milch-Sau* ... focus on user-friendly
- Allows flexibility

Answers

- Adapting patterns without recompile, data objects still accessible, equal interactors can have different patterns ...
- Not dependent on visualization (2D / 3D)
 - Change the data independent from visualization



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A Mealy state machine consists of:

- States
- •Events
- Transitions

State machine (Mealy)

Actions



Mealy: State is passive, transition causes change of data. (More: State is the active part)

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State machine



Has to have:

- •One start state
- •No dead state (not reachable)
- No magic state (transition leaves the state but can not be reached by others, not a start state)

- No dead loop
- Deterministic transitions (no equal transitions leading to different states)







Guard state: temporary state to check for a condition





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Classes in MITK to implement a state machine



<u>mitkState</u> <u>mitkTransition</u> <u>mitkAction</u>



According to a description several objects are instantiated and connected to each other during startup. Objects of type **mitkTransition** connect two objects of type **mitkState** in one direction (e.g. from state 1 to state 2). They contain the information on which event a state change may be done (EventID). They contain several objects of class **mitkAction** that specify the actions that are done after a state change.

All objects together represent the so called state machine pattern

```
MITK Interaction
```

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So, a state machine pattern defines the workflow of a special interaction procedure (e.g. interacting with a set of points).



. . .

All available patterns are loaded by a <u>StateMachineFactory</u> during startup (StateMachine.xml)

```
<stateMachine NAME="dumm example of the MITK state machine pattern xml syntax">
  <state NAME="first" ID="1" START STATE="TRUE">
    <transition NAME="to2" NEXT_STATE_ID="2" EVENT_ID="A">
      <action ID="X" />
    </transition>
    <transition NAME="to1" NEXT_STATE_ID="1" EVENT_ID="B">
      <action ID="\Phi" />
    </transition>
  </state>
  <state NAME="second" ID="2" >
    <transition NAME="to1" NEXT_STATE_ID="1" EVENT_ID="B">
      <action ID="Y" />
    </transition>
                                      Note: Also event IDs and action IDs
  </state>
                                                         are of type int in MITK
</stateMachine>
```

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State Machine Editor



See <u>related pages</u> for section State Machine Editor: graphical tool (eclipse plug-in) to create, modify and view state machine patterns



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Class <u>mitk::StateMachine</u> implements all methods for the use of a state machine.

class StateMachine : public itk::Object, public mitk::OperationActor
{

public:

virtual bool HandleEvent (StateEvent const *stateEvent);

•••

. . .

. . .

protected:

State machine logic

virtual bool ExecuteAction (Action *action, StateEvent const *stateEvent);

private:

std::vector<State::Pointer> m_CurrentStateVector;

...





mitk::Interactor is derived from mitk::StateMachine and adds dependency to one data.



```
MITK Interaction
```

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Derived classes



From mitk::Interactor derived classes add the implementation of actions that will lead to a change of data. Example:

```
class LightSwitch : public StateMachine
{
public:
  mitkClassMacro(LightSwitch, StateMachine);
  LightSwitch(const char*);
  bool DoSwitchOn(Action*, const StateEvent*);
  bool DoSwitchOff(Action*, const StateEvent*);
}
LightSwitch::LightSwitch(const char* type):StateMachine(type)
{
  CONNECT_ACTION( AcSWITCHON, DoSwitchOn );
  CONNECT_ACTION( AcSWITCHOFF, DoSwitchOff );
}
bool LightSwitch::DoSwitchOn(Action*, const StateEvent*)
{
  MITK_INFO<< "Enlightenment \n";
}
bool LightSwitch::DoSwitchOff(Action*, const StateEvent*)
{
   MITK_INFO << "Confusion n;
}
```





mitk::MyStateMachine::Pointer myStateMachine =
 mitk::MyStateMachine::New("myPattern", nodeOfData);

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Reuse of patterns



Because each object of type StateMachine pointers to one state of the specified state machine pattern, many objects can reuse one pattern.



Interaction-Pattern

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Doxygen mitk::StateMachine

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by 9/17/2010

MITK dkfz.

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How to administrate several interactors?

>Let one be the leader!

So many interactors!







- Administrates several state machines:
 - Interactors: Set onto one DataNode and thus associated to one data (e.g. PointSetInteractor to PointSet)
 - "Listeners": StateMachines that modify visualization, not data (e.g. CorrdinateSupplier for StatusBar)

```
class GlobalInteraction : public StateMachine
{
    public: ...
    void AddInteractor(Interactor* interactor);
    bool RemoveInteractor(Interactor* interactor);
    void AddListener(StateMachine* listener);
    bool RemoveListener(StateMachine* listener);
    ...}
```

An event is sent to all Listeners and only to the one Interacor, that float Interactor::CanHandleEvent(...) the best.



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Interaction sequence

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Operations

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Class <u>mitk::Operation</u> is a container for all information important for a change of data. Example:

...within MySpecialInteractor::ExecuteAction(...)





pointSet->ExecuteOperation(doOp);



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Undo / Redo functionality!

Why Operations?

Represents an extra layer between interaction classes taking care of changing data and data.











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```
...within MySpecialInteractor::ExecuteAction(...)
```

```
if (m_UndoEnabled)
```

Undo operations

```
PointOperation *undoOp = new mitk::PointOperation(
OpREMOVE, timeInMS, itkPoint, pointSet->Size());
```

```
OperationEvent *operationEvent =
```

```
new OperationEvent(pointSet, doOp, undoOp, "Add point");
m_UndoController->SetOperationEvent(operationEvent);
```

```
}
```

{

```
pointSet->ExecuteOperation(doOp);
```

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Undo:

- Offer flexible undo / redo functionality
 - Can be enabled and disabled. Thorough programming includes undo, rapid prototyping doesn't care about undo.
- Save memory resources

>Only store parameters how operations can be undone

If impossible (e.g. image filters), store backups if necessary





- http://www.mitk.org/wiki/Interaction_concept
- Doxygen documentation on mitkGlobalInteraction, mitkStateMachine
- Tutorial Step10 shows what to modify to add a new interactor